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Siddhant Chaudhary Adam (Adaptive Moment Estimation)

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 This is also called an *exponential decay moving average*; very old terms of the sequence are given exponentially small weight.

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- Adam has become the default method for many neural network packages these days!
- Easy to implement and very efficient, and magnitudes of parameter updates are invariant to scaling of the gradient.

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- At time *t*, we set the following.

$$m_t \leftarrow \beta_1 m_{t-1} + (1 - \beta_1) g_t$$
$$v_t \leftarrow \beta_2 v_{t-1} + (1 - \beta_2) g_t^2$$



• Here,  $g_t$  is the gradient at time step t, i.e  $g_t = \nabla_{\theta} f_t(\theta_{t-1})$ and the quantity  $g_t^2 = g_t \odot g_t$  denotes the coordinate-wise product.

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- Not a problem, as there are bias corrected estimates (we will see how these estimates come about).

$$\hat{m}_t \leftarrow \frac{m_t}{(1 - \beta_1^t)}$$
$$\hat{v}_t \leftarrow \frac{v_t}{(1 - \beta_2^t)}$$



$$\theta_t \leftarrow \theta_{t-1} - \alpha \cdot \frac{\hat{m}_t}{\sqrt{\hat{v}_t} + \epsilon}$$

.⊒ →



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- Adam uses ideas from two *techniques*: *momentum* and *adadelta*.
- Momentum ensures that when we are doing stochastic GD, by taking the whole history of gradients into account (moving averages), the current update will not jump around.
- Adadelta does the following: if the magnitude of gradient is large, we want to take small steps; if the magnitude is small, we want to take large steps.

#### Pseudocode

- 1: Input:  $\alpha$  and  $\beta_1, \beta_2 \in [0, 1)$ .
- 2: **Required**:  $f(\theta)$  (objective) and  $\theta_0$  (initial parameter)
- 3:  $m_0 \leftarrow 0$
- 4:  $v_0 \leftarrow 0$
- 5:  $t \leftarrow 0$
- 6: while (some convergence critrion on  $\theta_t$ ) do
- $\begin{array}{ll} 7: & t \leftarrow t+1 \\ 8: & g_t \leftarrow \nabla_{\theta} f_t(\theta_{t-1}) \\ 9: & m_t \leftarrow \beta_1 m_{t-1} + (1-\beta_1) g_t \\ 10: & v_t \leftarrow \beta_2 v_{t-1} + (1-\beta_2) g_t^2 \\ 11: & \hat{m}_t \leftarrow m_t / (1-\beta_1^t) \\ 12: & \hat{v}_t \leftarrow v_t / (1-\beta_2^t) \\ 13: & \theta_t \leftarrow \theta_{t-1} \alpha \hat{m}_t / (\sqrt{\hat{v}_t} + \epsilon) \end{array}$
- 14: end while